

ICoSR 2025

2025 4th International Conference on Service Robotics

Guangzhou, China July 25-27, 2025

CALL FOR PAPERS

- AI in Robot
- Cognition Based Interaction
- Ethical Issues
- Human Centred Robotics
- Human-Robot Collaboration
- Human Robot Integration
- Agriculture Robots
- Construction Robotics
- Search and Rescue Robotics
- Security Robotics
- Object Manipulation
- Robot Simulations
- Robot Software Development
- Robot Software Development
- Robots for Cultural Heritage
- Visual Servoing and Robot Vision

Special Sessions

- I : Assistive Service Robot for Healthcare in Aging Population
- II : Lightweight Design and Control Strategy for Assistive Exoskeletons
- III: Advanced Optimization Techniques in Service Robotics
- IV: Perception and Cognition in Intelligent Service Robotics
- V : Adaptive Motion Planning and Control for Service Robots
- VI: Rehabilitation Assistive Robot
- VII: International Symposium on Robotic Systems and Intelligent Perception
- VIII: Perception and Control of Intelligent Robots in Complex Environments

Submission

<https://cmt3.research.microsoft.com/4thICoSR2025>

Key Dates

The Final Round

Full Paper Submission Due: July 3, 2025

Organized by



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Keynote Speaker



Prof. Honghai Liu

Harbin Institute of Technology, Shenzhen, China
欧洲科学院院士(MAE), IEEE Fellow, IET Fellow



Prof. Ning Xi

The University of Hong Kong, China
IEEE Fellow



Prof. Jianbin Qiu

Harbin Institute of Technology, China
IEEE Fellow

Publication Information

All accepted and presented papers will be published in the ICoSR 2025 digital conference proceedings, and published in the Springer Book Series Lecture Notes in Networks and Systems (ISSN: 2367-3389), which will be sent for review and submitted for indexing by major citation databases such as Ei Compendex, Scopus etc.

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